

A C^∞ Spline Construction

P. Blass,

Department of Mathematics
Palm Beach Atlantic College

J. Dodziuk

Program in Mathematics
Graduate Center, CUNY

T.J Ford,

Department of Mathematics
Florida Atlantic University

J. Kolibal

Department of Mathematics
University of Southern Mississippi

Abstract

We consider the problem of determining a smooth spline through a set of points in the plane determined using a standard partition of unity of construction.

1. Introduction

Theorem 1 *Let a_0, a_1, a_2, \dots be a sequence of real numbers and d_0, d_1, d_2, \dots another sequence of real numbers defined by the formula*

$$\begin{aligned} d_0 &= \text{arbitrary, and} \\ d_i &= (a_{i+1} - a_{i-1})/2 \text{ for } i > 0 . \end{aligned} \tag{1}$$

(This is the 3-point midpoint formula for approximating the derivative at (i, a_i) .) Given $\epsilon > 0$, then there exists a function $f(x) \in C^\infty[0, \infty)$ satisfying

1. $f(i) = a_i$ for $i \geq 0$;
2. $f'(i) = d_i$ for $i \geq 0$;
3. $\sup_x |f(x) - l(x)| < \epsilon$ where $l(x)$ is the linear spline satisfying
 - (a) $l(i) = a_i$ for $i \geq 0$,
 - (b) $l(x)$ is linear on $[i, i + 1]$ for $i \geq 0$;

and,

4. On each interval $[i, i+1]$ for $i \geq 0$, $f(x)$ has at most one inflection point. More precisely, if m_i denotes the slope of $l(x)$ on $[i, i+1]$ then, $f(x)$ has no inflection points on $[i, i+1]$ provided $(d_i - m_i)(d_{i+1} - m_i) < 0$. On the other hand, if $(d_i - m_i)(d_{i+1} - m_i) \geq 0$, then $f(x)$ has a unique inflection point in $[i, i+1]$ at the midpoint $x = i + \frac{1}{2}$.

Proof. First we review the existence of certain C^∞ functions. Let

$$r(x) = \begin{cases} e^{-\frac{1}{x^2} - \frac{1}{(x-1)^2}} & \text{for } x \in (0, 1) \\ 0 & \text{otherwise} \end{cases} . \quad (2)$$

It is well known that $r(x)$ is infinitely differentiable at all points $x \in \mathbb{R}$. Let

$$t(x) = \left(\int_{-\infty}^{\infty} r(x) dx \right)^{-1} \int_{-\infty}^x r(u) du . \quad (3)$$

Then $t(x)$ is C^∞ , $t(x) = 0$ for $x \leq 0$, $t(x) = 1$ for $x \geq 1$ and $t'(x) = r(x) > 0$ if $0 < x < 1$. Note that derivatives of all orders (except zeroth) of $t(x)$ vanish at $x = 0$ and $x = 1$. All functions to be constructed in the proof of Theorem 1 will be built out of $t(x)$ by means of formulae. This will imply that all functions constructed below will depend continuously on the parameters of the construction.

Using affine transformations in x and in y ($= t(x)$), we see easily that for every interval $[a, b]$ and every pair of values $\alpha, \beta \in \mathbb{R}$ there exists a C^∞ function on \mathbb{R} , $j_\xi(x)$, $\xi = (a, b, \alpha, \beta)$ such that

$$\begin{aligned} j_\xi(x) &= \alpha \text{ for } x \leq a \\ j_\xi(x) &= \beta \text{ for } x \geq b \text{ and} \\ j'_\xi(x) &\neq 0 \text{ for } x \in (a, b) . \end{aligned} \quad (4)$$

Similarly, given $\zeta = (a, b, c, \alpha, \beta, \gamma)$, $a < b < c$, there exists a smooth function $k_\zeta(x)$ on \mathbb{R} with

$$\begin{aligned} k_\zeta(x) &= \alpha \text{ for } x \leq a \\ k_\zeta(x) &= \gamma \text{ for } x \geq c \text{ and} \\ k_\zeta(b) &= \beta . \end{aligned} \quad (5)$$

We can simply set

$$\begin{aligned} k_\zeta(x) &= j_{(a, b, \alpha, \beta)}(x) \text{ for } x \leq b \\ k_\zeta(x) &= j_{(b, c, \beta, \gamma)}(x) \text{ for } x \geq b . \end{aligned} \quad (6)$$

Clearly $k_\zeta(x)$ has the required properties.

Note that if ζ is as above and a, b, c, α, γ are kept fixed, then

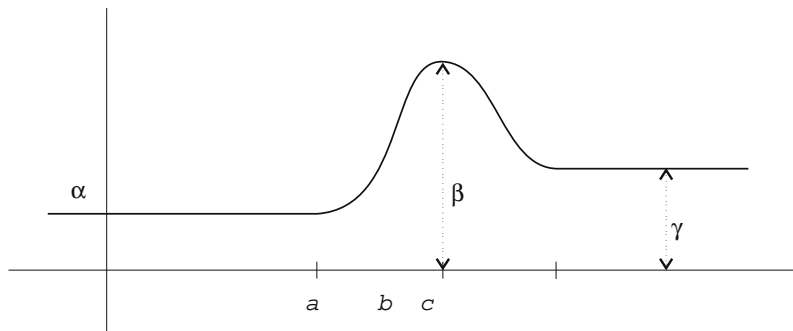


Fig. 1: $y = k_\zeta(x)$.

$$\lim_{\beta \rightarrow \infty} \int_a^c k_\zeta(x) dx = \infty . \tag{7}$$

This observation will be used repeatedly below.

2. Construction

We are now ready to start the construction. We will work on one interval $[i, i + 1]$ at a time and construct $f_i = f|_{[i, i + 1]}$ satisfying in addition to properties (1), (2), (3), (4) listed in the theorem, the property

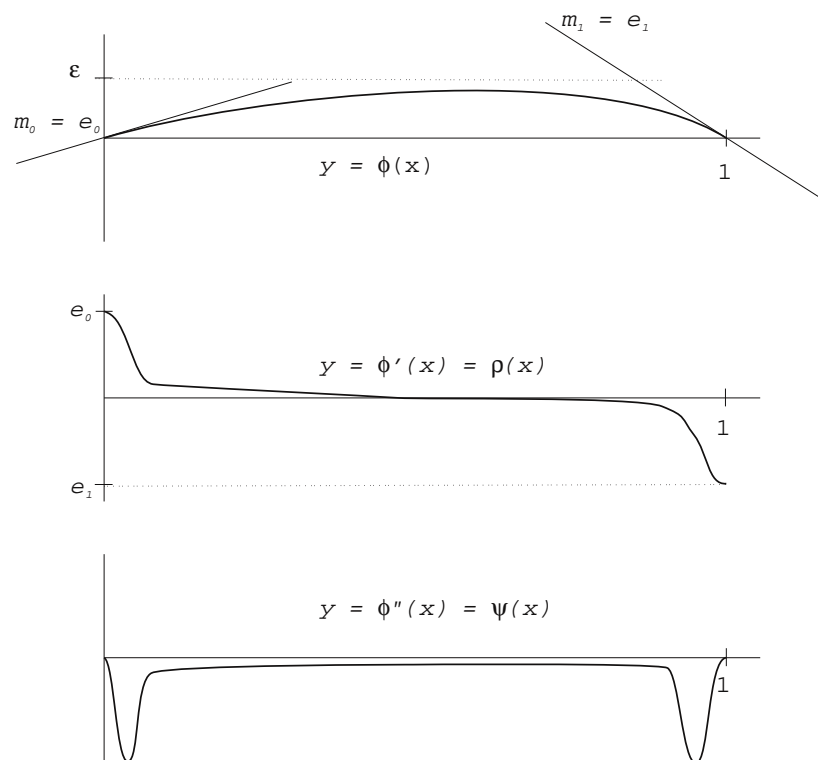
$$(5) \quad f_i^{(k)}(i) = f_i^{(k)}(i + 1) = 0 \text{ for all } k \geq 2.$$

Condition (5) will ensure that the f_i 's fit together smoothly. Now, since $l(x)$ is a known function, it is enough to construct $\phi_i = f_i - l_i$, where $l_i = l|_{[i, i + 1]}$. The properties that ϕ_i must satisfy are then

- (1') $\phi_i(i) = \phi_i(i + 1) = 0$
- (2') $\phi_i'(i) = e_i, \phi_i'(i + 1) = e_{i+1}$, where $e_i = d_i - m_i$ is prescribed.
- (3') $|\phi_i(x)| < \epsilon$ for every $x \in [i, i + 1]$
- (4') If $e_i \cdot e_{i+1} \geq 0$, then $\phi_i|_{(i, i + 1)}$ has exactly one inflection point located at $i + \frac{1}{2}$. If $e_i \cdot e_{i+1} < 0$, then $\phi_i|_{(i, i + 1)}$ has no inflection point.

Clearly it suffices to describe the construction of $\phi = \phi_0$. The same construction will work for every interval $[i, i + 1]$. The idea is to guess the shape of the graph of the second derivative of ϕ and integrate twice.

Case 1. Consider $e_0 \cdot e_1 < 0$. If necessary, multiply all functions by -1 , to be able to assume that $e_0 > 0, e_1 < 0$. The functions $y = \phi(x), y = \phi'(x) = \rho(x)$ and $y = \phi''(x) = \psi(x)$ have graphs that look like the following.

Fig. 2: The function ϕ and its first 2 derivatives.

The functions $\psi(x)$ and $\rho(x)$ must satisfy

$$\int_0^1 \psi(x) dx = e_1 - e_0 \quad (8)$$

$$\int_0^1 \rho(x) dx = 0 \quad (9)$$

$$\left| \int_0^x \rho(u) du \right| \leq \epsilon \text{ for all } x \in [0, 1] . \quad (10)$$

If this is the case, then

$$\rho(x) = e_0 + \int_0^x \psi(u) du , \quad (11)$$

$$\phi(x) = \int_0^x \rho(u) du \quad (12)$$

and ϕ satisfies the required properties.

We will take the widths of the two spikes, the values of ψ at the local minima and the value near $x = \frac{1}{2}$ as parameters and adjust them so that (8), (9) and (10) are satisfied. Thus, let η_0, η_1, μ be three (small) positive numbers and let h_0 and h_1 be two negative numbers. Define

$$\psi(x) = \begin{cases} k_{(0, \frac{\eta_0}{2}, \eta_0, 0, h_0, -\mu)}(x) & \text{for } 0 \leq x \leq \frac{1}{2} \\ k_{(1-\eta_1, 1-\frac{\eta_1}{2}, 1, -\mu, h_1, 0)}(x) & \text{for } \frac{1}{2} \leq x \leq 1 \end{cases} . \quad (13)$$

Thus η_0 and η_1 measure the widths of spikes, $-h_0$ and $-h_1$ are depths and μ is the depth of the horizontal portion of the graph. Given η_0, η_1, μ (provided μ is such that $0 < \mu \leq |e_1 - e_0|$) we can choose $h_0 = h_1 = h$ so that

$$\int_0^1 \psi(x) dx = e_1 - e_0 < 0 \quad (14)$$

This h is actually unique for a fixed choice of η_0, η_1, μ . Since e_0 and e_1 are fixed it is also obvious that (10) holds for all choices of η_0, η_1, μ which are sufficiently small. This is because η_0, η_1 and μ determine how closely the graph of $\rho(x)$ hugs the lines $x = 0, x = 1$ and $y = 0$. We still need to make sure that (9) holds. Suppose this is not the case for some choice of η_0 and η_1 and, for example,

$$\int_0^1 \rho(x) dx > 0 . \quad (15)$$

Let $\rho_+ = \frac{1}{2}(\rho + |\rho|)$, $\rho_- = \frac{1}{2}(|\rho| - \rho)$ be the positive and negative parts of ρ respectively. Then

$$\int_0^1 \rho_+(x) dx > \int_0^1 \rho_-(x) dx \quad (16)$$

by (15). First choose μ so that

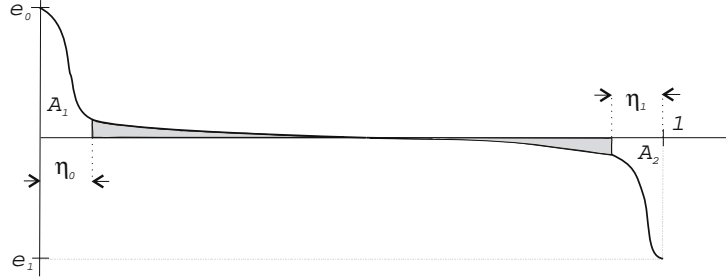
$$0 < \mu \ll \int_0^1 \rho_-(x) dx . \quad (17)$$

This makes the shaded area in Figure 3 negligible.

Now let η_0 approach zero keeping η_1 fixed. Clearly for η_0 sufficiently small $A_1 \ll A_2$ so that

$$\int_0^1 \rho(x) dx < 0 . \quad (18)$$

Therefore for some intermediate value of η_0

Fig. 3: The function ρ .

$$\int_0^1 \rho(x) dx = 0. \quad (19)$$

This finishes the construction in Case 1.

Case 2. Consider $e_0 \cdot e_1 \geq 0$. This is actually slightly easier. Suppose $e_0 \cdot e_1 > 0$. The case when one of the slopes is equal to 0 requires a modified argument and will be treated later. First consider the graphs.

In order for $\phi(x)$ to have all of the required properties, we must have conditions (8), (9) and (10) satisfied. We again try to construct ψ . Let η_0 , η_1 and η be parameters controlling the width of the spikes near 0, 1 and $\frac{1}{2}$ respectively. Only one parameter is needed in the middle since we require that

$$\eta\left(\frac{1}{2} - t\right) = -\eta\left(\frac{1}{2} + t\right) \quad (20)$$

for, say, $|t| < \frac{1}{4}$. Similarly let $\mu = |\psi(x)|$ for x near $\frac{1}{4}$ or for x near $\frac{3}{4}$. We need three more parameters that give the heights of spikes: h_0 , h_1 , and h . Observe that because of symmetry,

$$\int_0^1 \psi(u) du \quad (21)$$

is independent of h . Given η_0 , η_1 , η , h we can find h_0 and h_1 so that (8) holds. This is obvious. We can now vary h to achieve

$$\int_0^1 \rho_+(x) dx = \int_0^1 \rho_-(x) dx \quad (22)$$

